

The Hencky strain energy $\|\log U\|^2$ measures the geodesic distance of the deformation gradient to $SO(n)$ in the canonical left-invariant Riemannian metric on $GL(n)$

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1. Introduction

We show that the well-known isotropic Hencky strain energy $\mu\|\operatorname{dev} \log U\|^2 + \frac{\kappa}{2}[\operatorname{tr}(\log U)]^2$ for the symmetric Biot-stretch $U = \sqrt{F^T F}$ measures the geodesic distance of the deformation gradient $F \in GL^+(n)$ to $SO(n)$ where $GL^+(n)$ is viewed as a Riemannian manifold endowed with a left-invariant metric which is also right $O(n)$ -invariant (isotropic), and where the coefficients $\mu, \kappa > 0$ correspond to the shear modulus and the bulk modulus, respectively. Thus we provide yet another characterization of the polar-decomposition $F = RU$, $R \in SO(n)$, $U \in \operatorname{PSym}(n)$, since the stretch U provides also the geodesic distance to $SO(n)$ in the euclidean metric, i.e., $\operatorname{dist}_{\text{euclid}}^2(F, SO(n)) = \|U - \mathbb{1}\|^2$, with $\|X\| = \sqrt{\operatorname{tr}(X^T X)}$ denoting the Frobenius matrix norm henceforth. For both the euclidean and the geodesic distance, the orthogonal factor in the polar decomposition is the nearest rotation to F .

2. The geodesic distance to $SO(n)$

Viewing $GL(n)$ as a Riemannian manifold endowed with a left invariant metric

$$g_A : T_A GL(n) \times T_A GL(n) \rightarrow \mathbb{R} : g_A(X, Y) = \langle A^{-1}X, A^{-1}Y \rangle, \quad A \in GL(n), \quad (1)$$

for a suitable inner product $\langle \cdot, \cdot \rangle$ on the tangent space $T_{\mathbb{1}} GL(n) = \mathfrak{gl}(n) = \mathbb{R}^{n \times n}$ at the identity $\mathbb{1}$, the distance between $F, P \in GL^+(n)$ can be measured along sufficiently smooth curves. We denote by

$$\mathcal{A} = \{\gamma \in C^0([0, 1]; GL^+(n)) \mid \gamma \text{ piecewise differentiable}, \gamma(0) = F, \gamma(1) = P\} \quad (2)$$

the admissible set of curves connecting F and P , and by

$$L(\gamma) = \int_0^1 \sqrt{g_{\gamma(s)}(\dot{\gamma}(s), \dot{\gamma}(s))} ds \quad (3)$$

the length of $\gamma \in \mathcal{A}$. Then the geodesic distance $\operatorname{dist}_{\text{geod}}(F, P) = \inf_{\gamma \in \mathcal{A}} L(\gamma)$ defines a metric on $GL^+(n)$.

While it is generally difficult to explicitly compute this distance or to find length minimizing curves, it can be shown [1, 2] that if the Riemannian metric is defined by an inner product of the form

$$\langle X, Y \rangle = \langle X, Y \rangle_{\mu, \mu_c, \kappa} := \mu \langle \operatorname{dev} \operatorname{sym} X, \operatorname{dev} \operatorname{sym} Y \rangle_{n \times n} + \mu_c \langle \operatorname{skew} X, \operatorname{skew} Y \rangle_{n \times n} + \frac{\kappa}{2} \operatorname{tr} X \operatorname{tr} Y, \quad (4)$$

$$\|X\|_{\mu, \mu_c, \kappa}^2 := \langle X, X \rangle_{\mu, \mu_c, \kappa} = \mu \|\operatorname{dev} \operatorname{sym} X\|^2 + \mu_c \|\operatorname{skew} X\|^2 + \frac{\kappa}{2} [\operatorname{tr} X]^2,$$

$$\mu, \mu_c, \kappa > 0,$$

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which is the case if and only if g is right invariant under $O(n)$ [3], then every geodesic γ connecting F and P is of the form

$$\gamma(t) = F \exp(t(\text{sym } \xi - \frac{\mu_c}{\mu} \text{skew } \xi)) \exp(t(1 + \frac{\mu_c}{\mu}) \text{skew } \xi) \quad (5)$$

for some $\xi \in \mathfrak{gl}(n)$, where $\exp : \mathfrak{gl}(n) \rightarrow GL^+(n)$ denotes the matrix exponential, $\text{sym } \xi = \frac{1}{2}(\xi + \xi^T)$ the symmetric part and $\text{skew } \xi = \frac{1}{2}(\xi - \xi^T)$ the skew symmetric part of ξ . Now, according to the classical Hopf-Rinow theorem, there exists a length minimizing geodesic in \mathcal{A} . To obtain such a minimizer γ (and thus the distance $\text{dist}_{\text{geod}}(F, P) = L(\gamma)$), it therefore remains to find $\xi \in \mathfrak{gl}(n)$ with

$$P = \gamma(1) = F \exp(\text{sym } \xi - \frac{\mu_c}{\mu} \text{skew } \xi) \exp((1 + \frac{\mu_c}{\mu}) \text{skew } \xi). \quad (6)$$

Although no closed form solution to (6) is known, the equation can be used to obtain a lower bound¹

$$\inf_{Q \in SO(n)} \text{dist}_{\text{geod}}(F, Q)^2 \geq \inf_{Q \in SO(n)} \|\text{Log}(QF)\|_{\mu, \mu_c, \kappa}^2 \quad (7)$$

for the distance of $F \in GL^+(n)$ to $SO(n)$, as well as an upper bound

$$\text{dist}_{\text{geod}}(F, \text{polar}(F))^2 \leq \|\log(\text{polar}(F)^T F)\|_{\mu, \mu_c, \kappa}^2 = \mu \|\text{dev } \log(U)\|^2 + \frac{\kappa}{2} [\text{tr}(\log U)]^2, \quad (8)$$

where $F = RU$, $R = \text{polar}(F) \in SO(n)$, $U = \sqrt{F^T F} \in \text{PSym}(n)$ denotes the polar decomposition of F . Finally, we can use a recent optimality result proved by Neff et al. [4]:

Theorem 1. *Let $\|\cdot\|$ be the Frobenius matrix norm on $\mathfrak{gl}(n)$, $F \in GL^+(n)$. Then the minimum*

$$\min_{Q \in SO(n)} \|\text{Log}(Q \cdot F)\|^2 = \|\log(\sqrt{F^T F})\|^2 \quad (9)$$

is uniquely attained at $Q = \text{polar}(F)^T$.

A consequence of Theorem 1, combined with (7) and (8), yields the main result [5]:

Theorem 2. *Let g be a left invariant Riemannian metric on $GL(n)$ that is also right invariant under $O(n)$, and let $F \in GL^+(n)$. Then:*

$$\text{dist}_{\text{geod}}(F, SO(n))^2 = \text{dist}_{\text{geod}}(F, \text{polar}(F))^2 = \mu \|\text{dev } \log(U)\|^2 + \frac{\kappa}{2} [\text{tr}(\log U)]^2. \quad (10)$$

Furthermore, for $\mu_c = 0$ (in which case $\text{dist}_{\text{geod}}$ defines a pseudometric on $GL^+(n)$), Theorem 2 still holds.

References

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¹We denote by \log the principal matrix logarithm, while the expression Log is used to indicate that the infimum is taken over the whole inverse image under \exp , i.e. $\inf_{Q \in SO(n)} \|\text{Log}(QF)\|_{\mu, \mu_c, \kappa}^2 = \inf\{\|X\|_{\mu, \mu_c, \kappa}^2 : X \in \mathfrak{gl}(n), \exp(X) = QF\}$.